

# Missiles and launchers

## *Detailed testing capabilities*

Model type	Model rigging	Wind tunnel	Typical test program	Test objective	Mach number range
Full scale model. Maximum length: 6 m.	Straight sting.  Top wall mast mounting.	<a href="#">S1MA</a>	<ul style="list-style-type: none"> <li>• <math>\alpha</math> sweep polars.</li> <li>• <math>\beta</math> sweep polars</li> </ul> internal flow variations.	<ul style="list-style-type: none"> <li>• Missile loadings.</li> <li>• Air intake performance.</li> <li>• Engine operation.</li> <li>• Infrared signature.</li> <li>• Dynamic wing opening.</li> <li>• Missile head drop test.</li> </ul>	$M < 1$
Full model. Typical diameter: 110 mm.	Straight sting. With / without jet simulation (hot or cold gas).	<a href="#">S2MA</a>	<ul style="list-style-type: none"> <li>• <math>\alpha</math> sweep polars.</li> <li>• <math>\beta</math> sweep polars.</li> <li>• Roll polars.</li> <li>• Internal flow.</li> </ul>	<ul style="list-style-type: none"> <li>• Fin loading.</li> <li>• Full model loading.</li> <li>• Pressure distribution.</li> <li>• Booster separation (with CTS).</li> <li>• Jet simulation (hot and cold gas).</li> </ul>	$0,2 < M < 3,1$
Full model. Typical diameter: 200 mm.	$\alpha/\beta$ support With / without jet simulation (hot or cold gas).	<a href="#">S4MA</a>	<ul style="list-style-type: none"> <li>• <math>\alpha</math> sweep polars.</li> <li>• <math>\beta</math> sweep polars.</li> <li>• Internal flow.</li> </ul>	<ul style="list-style-type: none"> <li>• Full model loading.</li> <li>• Jet simulation (hot and cold gas).</li> </ul>	$2 < M < 12$
Isolated air intake model.	Standard sting holder. Mass flow control and measurement units.	<a href="#">S2MA</a>	<ul style="list-style-type: none"> <li>• Internal flow characteristics.</li> <li>• <math>\alpha</math> sweep polars.</li> <li>• <math>\beta</math> sweep polars.</li> </ul>	Air intake performance (efficiency, steady distortion).	$0,2 < M < 3,1$
Rotating model.	Self rotating model. Actuated roll motion.	<a href="#">S2MA</a>	<ul style="list-style-type: none"> <li>• <math>\alpha</math> sweep polars.</li> <li>• <math>\beta</math> sweep polars.</li> </ul>	Full model loading.	$0,2 < M < 3,1$
Full model (typical diameter: 70 mm).	Sting mounted, with / without jet simulation (hot or cold).	<a href="#">S3MA</a>	<ul style="list-style-type: none"> <li>• <math>\alpha</math> sweep polars.</li> <li>• Roll polars.</li> </ul>	<ul style="list-style-type: none"> <li>• Fin loading.</li> <li>• Full model loading.</li> </ul>	$0,1 < M < 5,5$
Model parts (wings, fins,...).	Wall mounted.	<a href="#">S3MA</a>	$\alpha$ sweep polars.	<ul style="list-style-type: none"> <li>• Model loads.</li> <li>• Pressure distribution.</li> </ul>	$0,1 < M < 5,5$
Air intake model (isolated or model integrated)	Sting or strut mounted.	<a href="#">S3MA</a>	Internal flow characteristics.	Air intake performance.	$0,1 < M < 5,5$
Full model for dynamic derivative measurements	Specific rigs: - pitching moment, - roll moment (100Hz).	<a href="#">S3MA</a>	<ul style="list-style-type: none"> <li>• Pitch and pause.</li> <li>• <math>\alpha</math> sweep polars.</li> </ul>	Model dynamic stability coefficients.	$0,1 < M < 5,5$
Full model for Magnus effects	Specific rigs: roll motion (400Hz).	<a href="#">S3MA</a>	• $\alpha$ sweep polars.	Side force induced effect on rotating missiles.	$0,1 < M < 5,5$
Nozzles	Wall mounted balance. Supply pipe equipped with strain gages and accelerometers.	<a href="#">S4b</a>	<ul style="list-style-type: none"> <li>• Mass flow variation.</li> <li>• Very high pressure ratio.</li> </ul>	<ul style="list-style-type: none"> <li>• Steady thrust measurement.</li> <li>• Unsteady loads on nozzle.</li> </ul>	

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Radome scaled down model.	Sting mounted, specific rig.	<a href="#">S3MA</a>	Analysis of rain or sand impact.	Erosion effects.	0,1<M<5,5
Nozzles / afterbodies tests with heated core and secondary floors		<a href="#">BD2</a>		nozzle and afterbody performances	