



From multi to many-core: network on chip challenges

On-board software and multicores : opportunities and issues
CCT SIL-IRE, Mardi 16 Juin 2015

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ONERA – The French Aerospace Lab

June 16, 2015



re t o u r s u r i n n o v a t i o n

ONERA - Paris Saclay

- exact information are not always public
- the meaning of words sometimes (...) differs
- personal experience on limited set of chips

A good overview: "ISSCC TRENDS" <http://isscc.org/trends>

This and other related topics have been discussed at length at ISSCC 2015, the foremost global forum for new developments in the integrated-circuit industry.

Next session: Jan. 31 – Feb. 4 2016, San Francisco, CA
<http://isscc.org>

ONERA experience I

ONERA has been involved in several many-core projects

- MARC (2009-2012): Intel Many-Core Application Research Community academic program
- MACSIMA (2013-2017): ONERA internal research project
 - topic: radar, planification and control-command application on the same many-core
- DREAMS (2013-2017): FP7 European project
 - topic: mixed-criticality on multi-core
 - partners: Univ. Siegen, Ikerlan s. coop, Thales, ONERA, RealTime-At-Work, TTTech, Technische Univ. Kaiserslautern, Fortiss, Sintef, Alstom, STMicroelectronics, Virtual Open Systems, Technological Educational Institute of Crete, Polytechnic Univ. of Valencia, Fentiss, TUV
- CAPACITÉS (2014-2018): LEOC (Logiciel Embarqué et Objets Connectés) french-founded project,

- topic: multicore for critical embedded systems
- partners: Airbus, Airbus Helicopter, ARMINES, Dassault Aviation, Inria, IRISA, IRIT, IS2T, Kalray, MBDA, ONERA, OpenWide, Probayes, Real-Time At Work, Safran, Supersonic Imagine, TIMA, Verimag

15 publications (2011-2015):

[16, 19, 23, 17, 20, 15, 21, 3, 1, 8, 6, 7, 11, 13, 14]

Outline

Many-cores are arriving

Trends

Network on Chip

Overview

Routing

Contention

Other solutions

Tiles

Three selected solutions

Intel SCC

Spidergon STNoC

The Kalray MPPA

A real-time NoC ?

Conclusion

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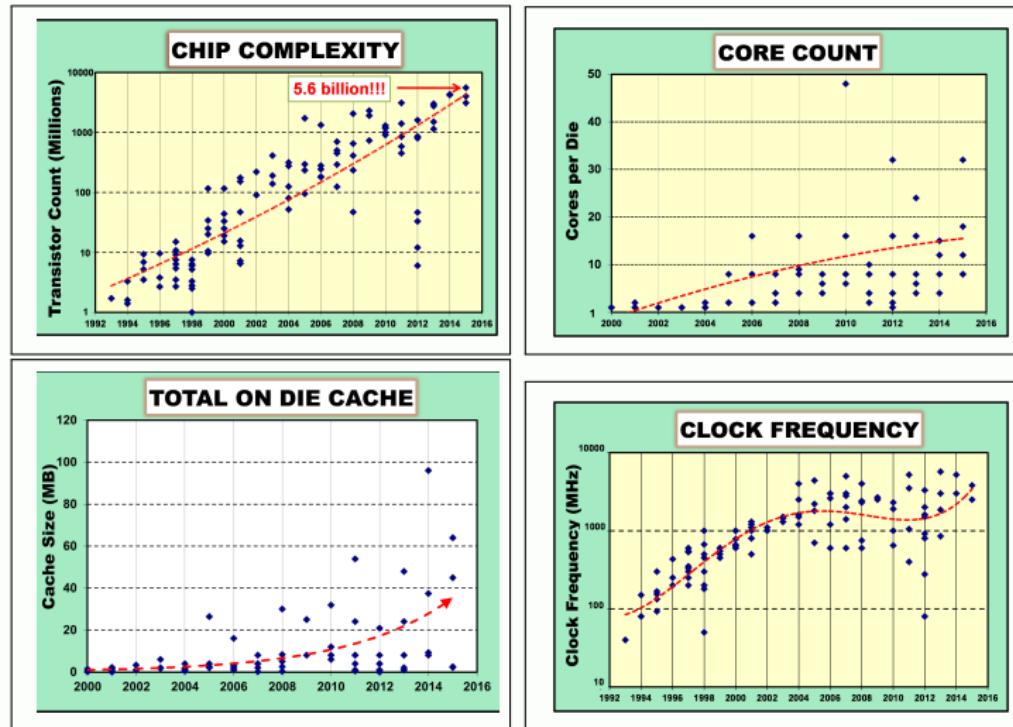
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Some trends [25]



Cache memory

More cores, and more cache

- cache consumes few energy
- cache is efficient

But...

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But...

- how to ensure cache coherency with 32 cores ?

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- how to ensure cache coherency with 32 cores ?
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- implicit or explicit communications ?
 - message passing vs shared memory

More cores, and more cache

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But...

- how to ensure cache coherency with 32 cores ?
- why ?
- local cache or local memory ?
- implicit or explicit communications ?
 - message passing vs shared memory
- an old/new programming way

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- how to connect chip elements ?
- NoC for SoC vs NoC for multicore
 - homogeneous vs heterogeneous system
 - access to main memory and IO
- different approaches depending on manufacturer
- less information than on cores

From bus to NoC

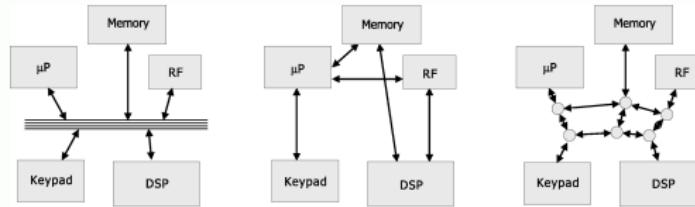


Figure : From bus to NoC [2]

- Bus: shared resource
- Pt-to-pt: does not scale
- NoC:
 - set of shared resources
 - allow parallel communications

A common vocabulary

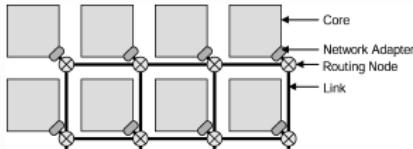


Figure : Architecture elements[2]

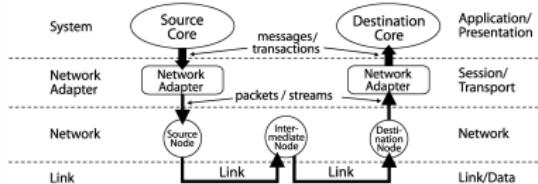
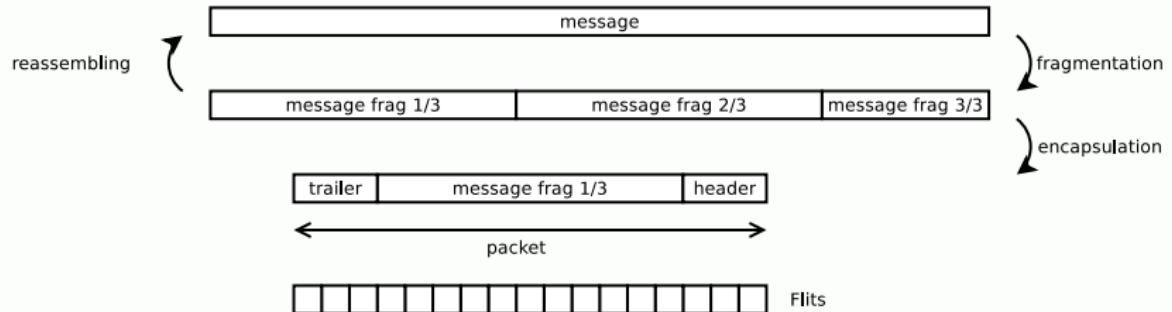


Figure : Network layers [2]

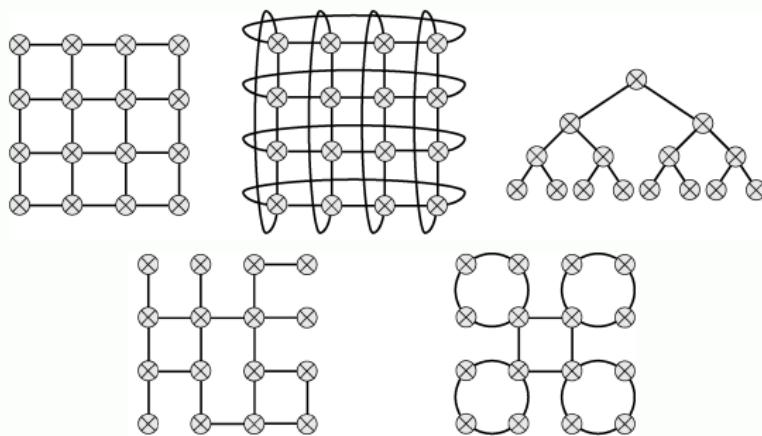
- Core/tile: could be also IO/RAM
 - write/read messages
- Network adapter
 - fragment/reassemble messages into packets
 - send/receive packets
 - flow control
- Routing node: commutation element
 - send/receive *flits* ($\approx 64\text{bits}$)
 - also flow control

Data vocabulary



- Core/tile: could be also IO/RAM
 - write/read messages
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Topologies



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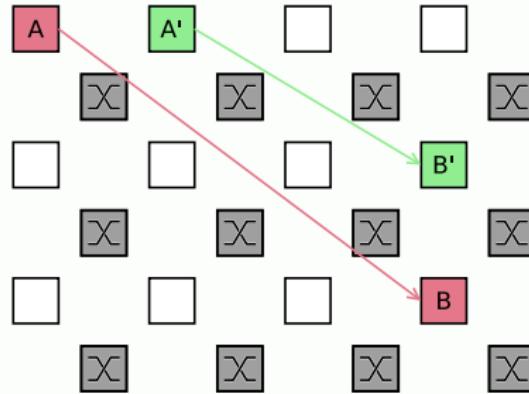
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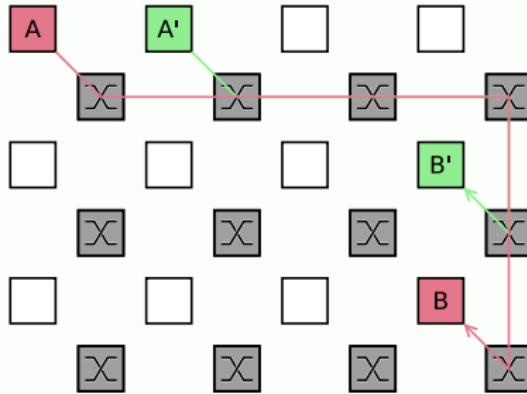
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Routing:

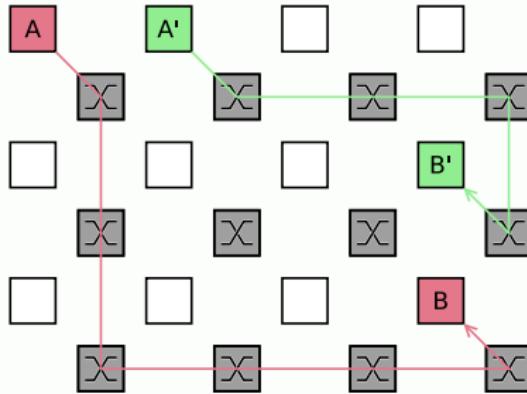
Routing



Routing:

- XY: follows the row first, then moves along the column
Note: reverse communication uses another path

Routing

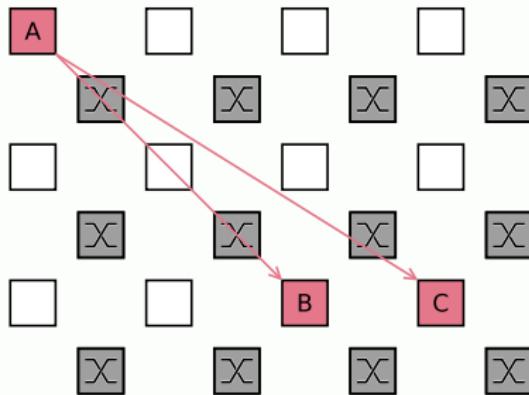


Routing:

- XY: follows the row first, then moves along the column
Note: reverse communication uses another path
- Source routing: source set the path in the header

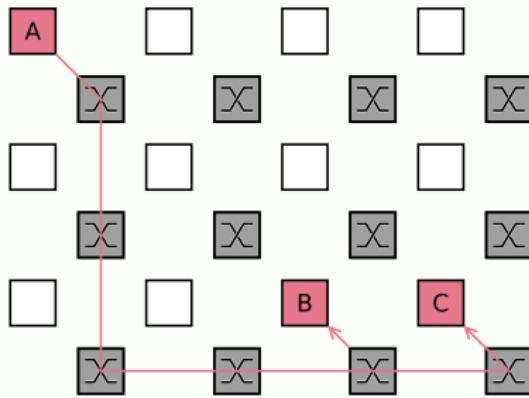
Routing:

- XY: follows the row first, then moves along the column
Note: reverse communication uses another path
- Source routing: source set the path in the header
- Adaptative:
 - route computed “on the fly”
 - minimize link/router load
 - research only ?



Multicast: sending the same data to several cores

- multicast NoC: data send once, path sharing
- non multicast NoC: data sent several times, path competition



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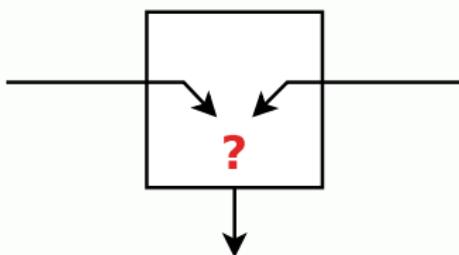
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Router: managing contention



They always are contentions

- arbitration is needed
 - ⇒ link scheduling policy
 - ⇒ storage is needed
 - ⇒ memory allocation policy
such memory is expensive
- ⇒ large set of solutions

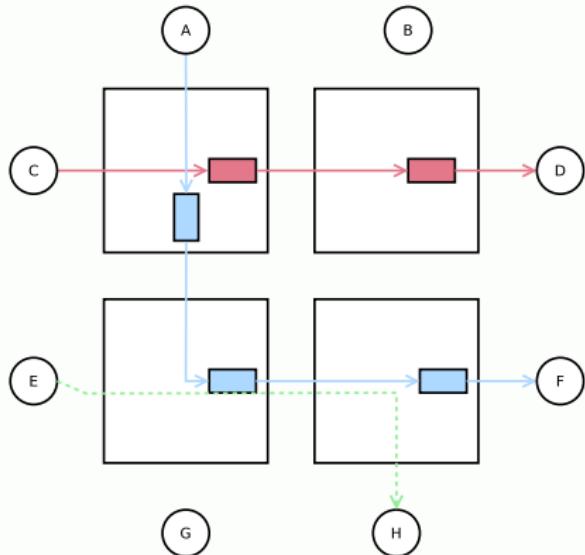
Forwarding: how to transmit data?

- store & forward
- wormhole
- virtual circuit
- virtual cut-through

Store and forward

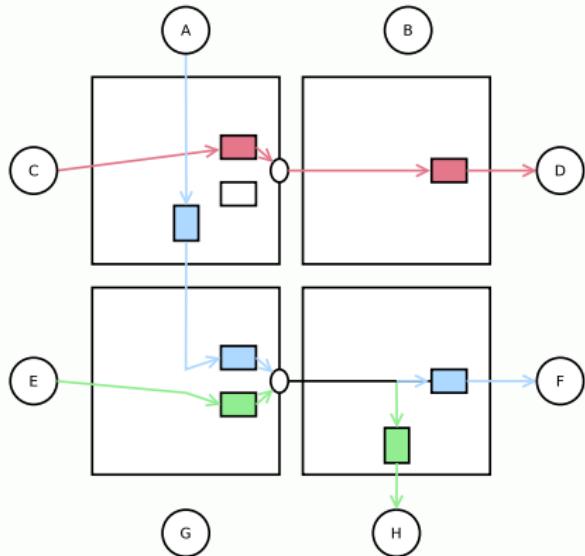
- common policy in network
- send and store full packets in routers
- require buffer size many times larger than packet size

Wormhole forwarding



- like Spacewire
- forward flits even while receiving
- send flits up to blocking
- ⇒ link flow control
- allow large messages / packets
- implies blocking, and even dead-locks

Virtual circuit enhancement



- reduces blocking
- require more logic
 - flit tagging
 - VC id allocation
 - memory sharing
 - arbitration policy
- allows per VC QoS

Virtual cut-through forwarding

- looks like wormhole restriction

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- or store&forward enhancement

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Virtual cut-through forwarding

- looks like wormhole restriction
 - or store&forward enhancement
 - send packet only if enough space in next router
- ⇒ require storage of full packet

Forwarding: feedback

Forwarding	Per node cost		
	Latency	Memory	
store & forward	packet	packet	Common in networks
wormhole	header	header	Blocking
virtual cut-through	header	packet	A trade-off (?)

- wormhole has good mean performances
 - ... but can lead to dead-locks
- virtual circuit has less blocking
 - ... but require more memory and logic
- store& forward / virtual cut-through are well known
 - ... but require more memory or small messages

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The time-triggered approach

Build a global TDMA schedule

- + avoid any contention
- + small network delays
- require periodic tasks/communications
- does it scale ?

Avoid contention in network, by establishing core-to-core connection, and resource reservation.

- increases latency (connection establishment)
- increases logic
- research only ?

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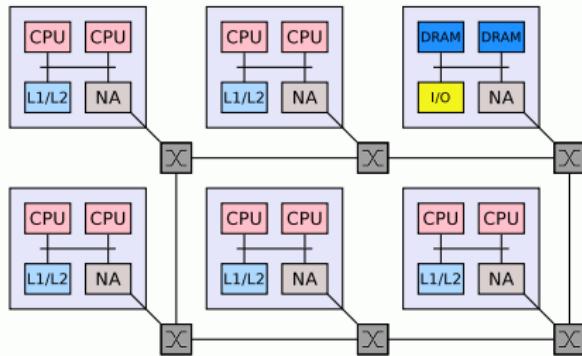
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Tile-based solutions



- Initial architecture: [24], MIT, 2007
- Tile:
 - local multi-core
 - DRAM, I/O...
- NoC between tiles
- Hierarchical design
 - ⇒ multi-core interferences + NoC interferences

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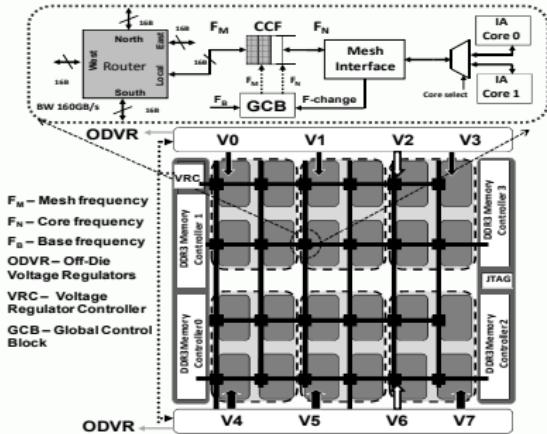
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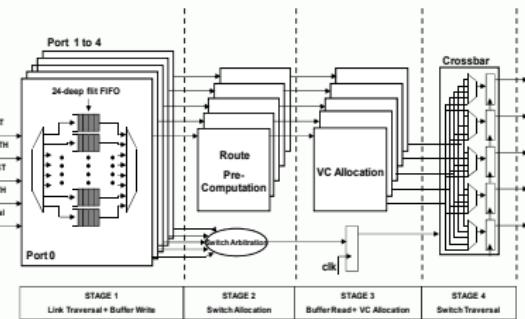
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Intel SCC architecture



- experimental processor [22]
- 24 tiles
- 2 cores per tile
- 2Tb/s bisection bandwidth
- explicit message passing (but virtual global addressing)

Intel SCC router



- Virtual Circuit forwarding
- 8 VC for the whole router
- crossbar output

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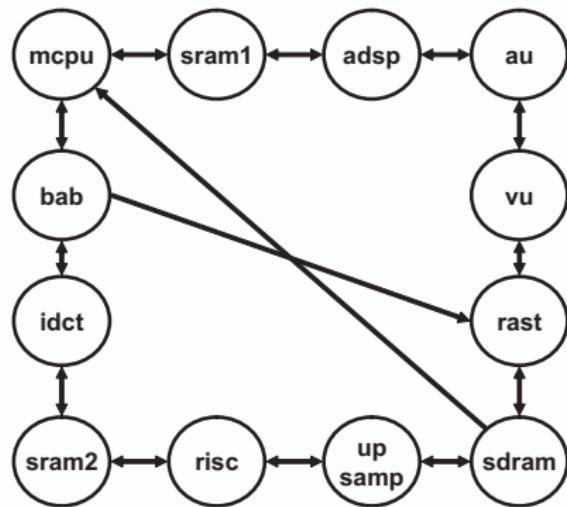
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Spidergon STNoC



- A NoC for SoC (?) [5, 18]
- application specific topology
- Time-Triggered scheduling soon

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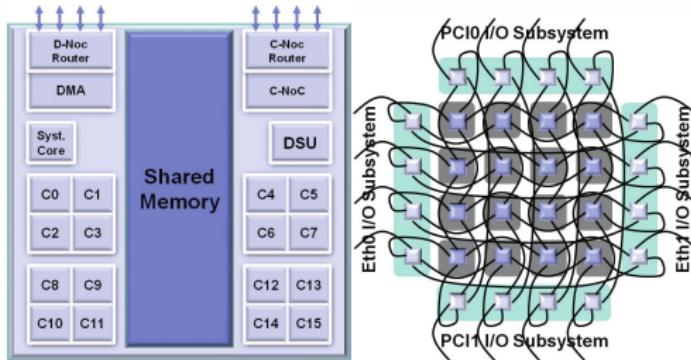
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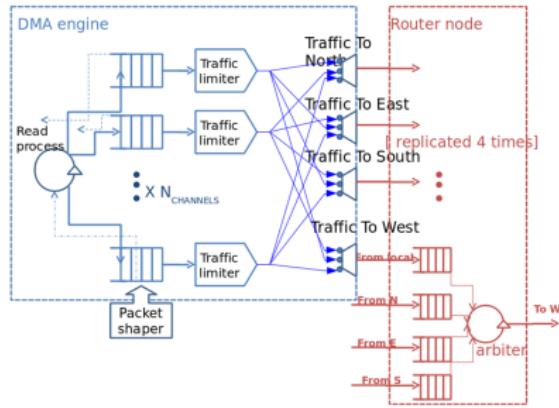
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Kalray architecture



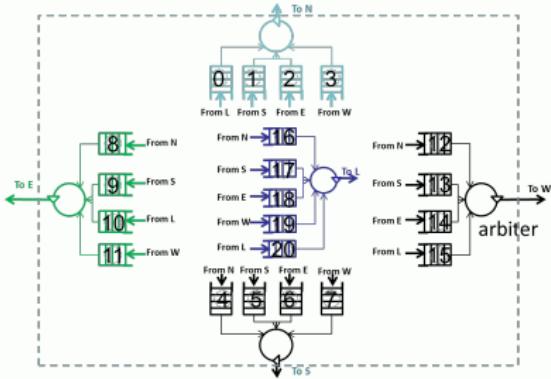
- A 256-cores chip [9]
- torus topology
- 16 tiles
- 16 “simple” cores per tile

Kalray Network Adapter



- 8 channels [10]
 - explicit communications
 - per channel traffic limiter
- ⇒ HW support for latency computation

Kalray Network router



- virtual cut-through forwarding
- round-robin arbitration

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Real-time with NoC?

Challenge:

- bound Worst case Interference Time (WCIT)
- ⇒ bound NoC Worst Case Traversal Time (WCTT)

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Real-Time NoC:

- there will be one: TT extension of STMicro Spidergon STNoC
- there are some HW mechanisms
 - deactivation of cache coherency
 - bandwidth limiters

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Solutions:

- execution model
- analyse methods

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The bad news

The good news

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- no large real-time processor market

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The times they are changing

- from shared memory to message passing

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Why multi-cores

Theoretical limits

Architecture impact

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Why multi-cores

Theoretical limits

Architecture impact

Some limits [4, 12]

Moore's law

The transistor density doubles every generation.

Pollack's rules

Performance (of a single core) is roughly proportional to *square root* of the number of transistors.

More limits [4, 12]

Amdahl's law

Given a program, with fraction $f \in [0, 1]$ that can be executed in parallel. Then, the speed-up with n cores is bounded by

$$\frac{1}{(1 - f) + \frac{f}{n}} \quad (1)$$

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More limits [4, 12]

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Corollary

With more processors, programmers find more parallelism in problems...

Power consumption

$$W = CV^2f$$

The capacity (C) is technology dependant.
Cache memory uses few energy.

	Power	GFlop/Watt
Mono/Quadri-Core	150W	7GF/W
GPGPU	300W	10GF/W
Many-core	30W	70GF/W

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Why multi-cores

Theoretical limits

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Symmetric multicores ?

Forecast [12, 4]: next chips will have

- a few “large” cores for sequential part
- several “small” cores for parallel part
- on the same chip ? (multi-core vs GPGPU)

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